



The Pursuit of Knowledge: Discovering and Localizing Novel Categories using Dual Memory

Sai Saketh Rambhatla¹, Rama Chellappa^{1,2} and Abhinav Shrivastava¹
¹University of Maryland, College Park ²Johns Hopkins University



Goal: **Discover** novel objects and learn models to detect them **without** human supervision.

Shortcomings of standard supervised paradigm

Training set (VOC) Testing on: VOC COCO

Detectors trained on a labeled dataset (VOC)
Fail to detect **novel** objects (e.g., additional objects in COCO)

Our Discovery and Localization Benchmark & Framework

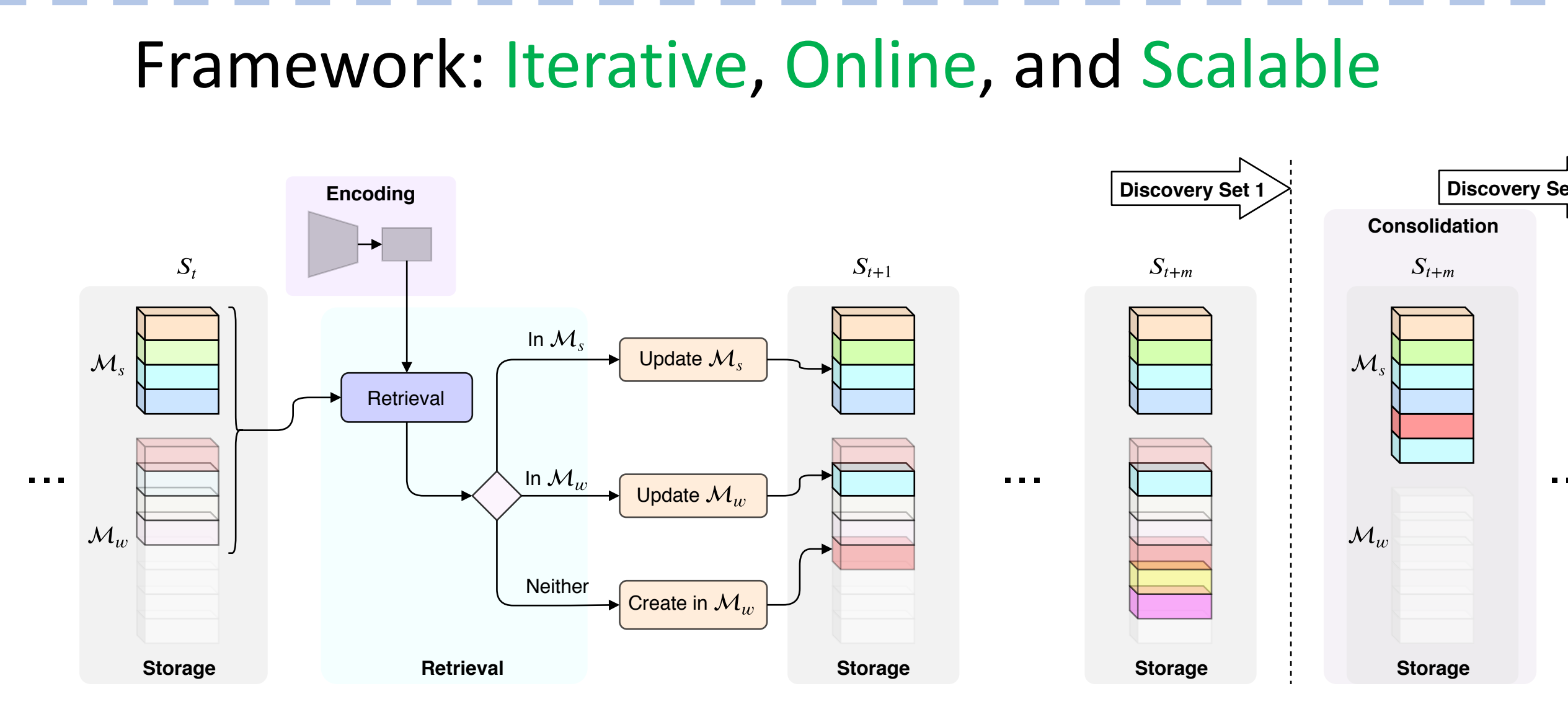
Discovered and localized examples of *unknown* classes (from COCO). In this illustration these correspond to (clockwise): traffic-light, tie, umbrella, bear

- ★ **Large-scale, realistic benchmark** for object discovery & localization
- ★ **Scalable never-ending in-the-wild** concept discovery framework

Shortcomings of contemporary discovery methods

Tailored for **co-segmentation/localization** **Not scalable**
 [Cho et al., CVPR 2015] [Vo et al., CVPR 2019] [Vo et al., ECCV 2020]

Dual Memory Framework for Unsupervised Object Discovery



Encoding: Region Proposals
Storage: Dual Memory
Retrieval: Decide seen/unseen?

Dual Memory

Contains clusters (“**slots**”), represented as a **Centroid** or a **Classifier**

Centroid	Classifier
• Fast updates	• Slow updates
• Inaccurate	• Accurate
• Cos. similarity	• Cls. score

Semantic Memory	Working Memory
• Long-term memory	• Short-term memory
• “ Semantic Prior ” init.	• Null init.,
• Reliable associations	• Unreliable associations
• Infrequent updates	• Frequent updates
➤ Classifier	➤ Centroid

Benchmark Details and Results

Benchmark

- Labeled datasets:**
- ImageNet
 - Pascal VOC
- In-the-wild discovery dataset:** COCO
- Salient features:**
- Large-scale
 - Different distribution of labeled & discovery set
 - Localization

Metrics

- Our benchmark:**
- Purity vs. Coverage
 - mAP for learned detectors
 - # of objects discovered
- Other methods*:**
- CorLoc
 - CorRet
 - Det-Rate
- *None evaluates discovery performance

Smaller-scale Object discovery on subsets of COCO train2014. Comparison with contemporary discovery methods using AuC for *unknown* classes.

Method	Conf.	#imgs.	CorLoc	CorRet	DetRate
Vo et. al	CVPR’19	2.5k	6.62	80.00	4.73
Vo et. al [†]	CVPR’19	2.5k	6.34	70.00	5.17
Ours		2.5k	43.00	64.22	48.56
Vo et. al	ECCV’20	20k	15.77	100	11.56
Ours		20k	41.41	64.60	46.81

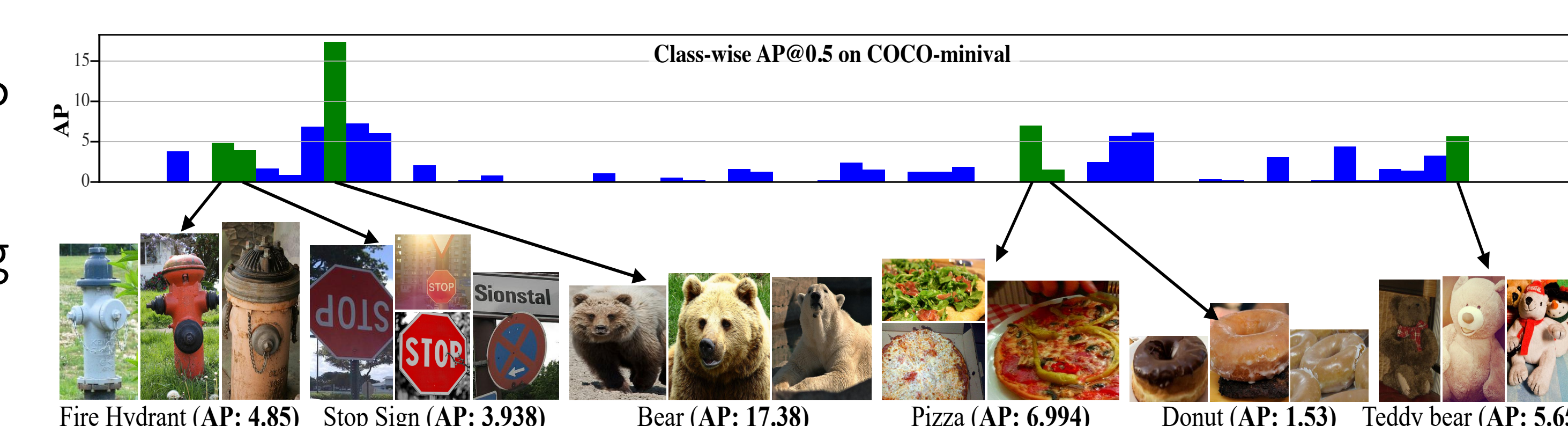
[†]: OSD with ResNet-101 Faster R-CNN proposals and classification-head features (same as Ours).

Detection performance (mAP) for object detectors on COCO minival, trained using *oracle* labels for clusters.

Classes	GT-IoU: 0.5		GT-IoU: 0.2	
	AP@0.5	AP@0.2	AP@0.5	AP@0.2
All (80)	2.69	4.44	2.62	4.37
Novel (60)	1.87	3.50	1.76	3.42
Novel [†]	5.23	6.47	5.45	6.40

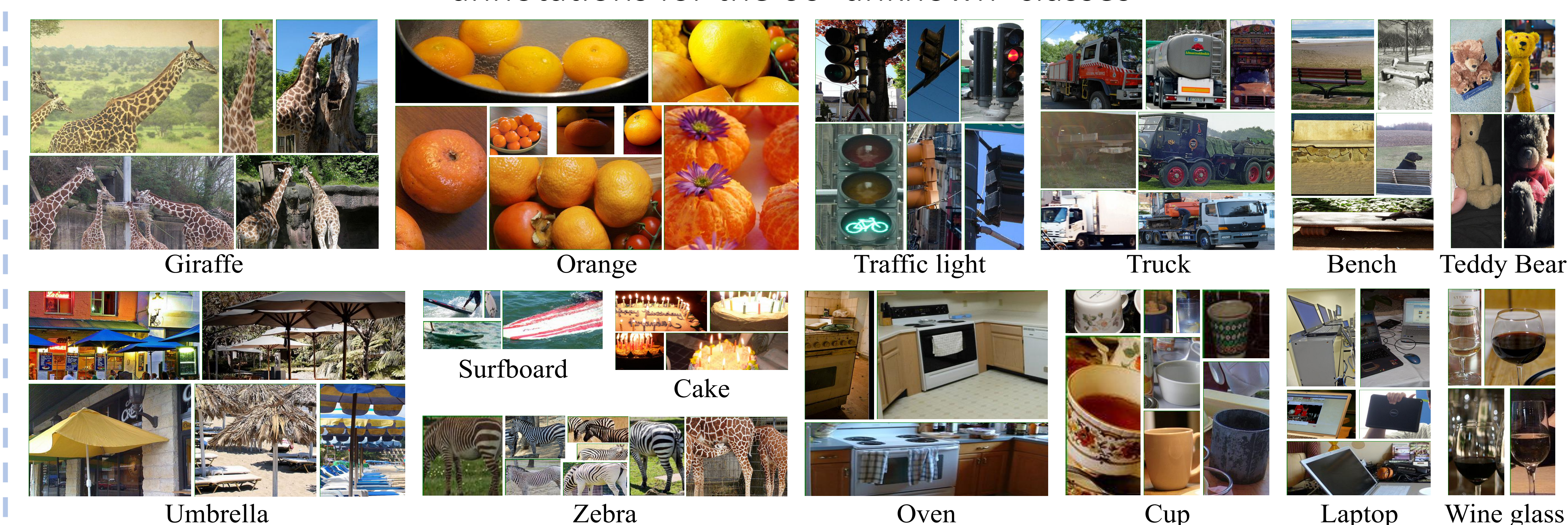
[†]: mAP of classes with AP greater than chance.

Sample detections and class-wise AP on COCO minival using our object detectors trained novel classes using *oracle* labels.



Concepts discovered by our approach which we cannot evaluate since they are unlabeled

Concepts discovered by our approach which we can evaluate using the ground-truth annotations for the 60 ‘unknown’ classes



Visit the website for more discovered objects:



Large-scale Object discovery on the entire COCO train2014 (80k images). Comparisons with scalable clustering methods using AuC for *unknown* classes.

Method	AuC@0.5	AuC@0.2	#disc. objs
K-means	3.34	7.23	42
FINCH	3.03	6.99	42
Ours	3.60	9.11	46